III. Posterior and Prior Distributions - Basic Setup -

A. Let θ and **Y** be two events, then in classical probability theory:

$$\mathbf{P}(\boldsymbol{\theta}|\mathbf{Y}) = \frac{P(\boldsymbol{\theta} \cap \mathbf{Y})}{P(\mathbf{Y})} \quad \text{and} \quad \mathbf{P}(\mathbf{Y}|\boldsymbol{\theta}) = \frac{P(\boldsymbol{\theta} \cap \mathbf{Y})}{P(\boldsymbol{\theta})}$$

hence

$$P(\theta \cap Y) = P(\theta|Y)P(Y) = P(Y|\theta)P(\theta)$$

and

$$\mathbf{P}(\boldsymbol{\theta}|\mathbf{Y}) = \frac{\mathbf{P}(\mathbf{Y} \mid \boldsymbol{\theta})\mathbf{P}(\boldsymbol{\theta})}{\mathbf{P}(\mathbf{Y})}$$

In the Bayesian framework, **Y** is the observed data, the θ are the parameters, **P**(**Y**| θ) is the joint distribution of the sample, **P**(θ) is the *prior distribution* of the parameters, **P**(**Y**) is the marginal distribution of the sample, and **P**(θ |**Y**) is the *posterior distribution*. Because **P**(**Y**) is a constant, the posterior distribution is proportional to the product of the joint distribution of the sample (which is proportional to the likelihood function) and the prior distribution; that is:

$$P(\theta|Y) \propto P(Y|\theta)P(\theta)$$

B. Suppose we have a *random sample* (a set of independent and identically distributed random variables) from a probability distribution $f(x|\theta)$. Then the joint distribution of the sample is:

$$f_n(x_1, x_2, x_3, \dots, x_n|\theta) = f_n(\underline{x}|\theta) = \prod_{i=1}^n f(x_i\theta)$$

This is commonly referred to as a *likelihood function*. (Technically, when $f_n(\underline{x}|\theta)$ is regarded as a function of θ for a given vector \underline{x} , it is called a likelihood function. Note that θ is *not* a random variable in this context.) If θ is a random variable then $f_n(\underline{x}|\theta)$ is equal to the ratio of the joint distribution of the sample and θ to the marginal distribution of θ using the standard formula for conditional probability:

$$f_{n}(x_{1}, x_{2}, x_{3}, ..., x_{n} | \theta) = \frac{h(x_{1}, x_{2}, x_{3}, ..., x_{n}, \theta)}{\xi(\theta)}$$

and

$$h(x_1, x_2, x_3, ..., x_n, \theta) = f_n(x_1, x_2, x_3, ..., x_n | \theta)\xi(\theta)$$

where $\xi(\theta)$ is the probability distribution of θ . In the Bayesian framework $\xi(\theta)$ is known as the *prior distribution of* θ .

The *posterior distribution*, the probability distribution of θ given the vector $\underline{\mathbf{x}}$, $\boldsymbol{\xi}(\boldsymbol{\theta}|\underline{\mathbf{x}})$, is the ratio of the joint distribution of $\underline{\mathbf{x}}$ and $\boldsymbol{\theta}$, $\mathbf{h}(\underline{\mathbf{x}}, \boldsymbol{\theta})$, and the marginal distribution of the sample. The marginal distribution of the sample is:

$$g_{n}(x_{1}, x_{2}, x_{3}, ..., x_{n}) = \int_{\theta} h(x_{1}, x_{2}, x_{3}, ..., x_{n}, \theta) d\theta = \int_{\theta} f_{n}(x_{1}, x_{2}, x_{3}, ..., x_{n}|\theta) \xi(\theta) d\theta$$

Applying the standard formula for conditional probability:

$$\xi(\theta | x_1, x_2, x_3, \dots, x_n) = \frac{f_n(x_1, x_2, x_3, \dots, x_n | \theta)\xi(\theta)}{g_n(x_1, x_2, x_3, \dots, x_n)}$$

which is in the same form as Bayes Theorem. Stated more compactly:

$$\xi(\boldsymbol{\theta}|\underline{\mathbf{x}}) = [\mathbf{f}_{n}(\underline{\mathbf{x}}|\boldsymbol{\theta})\xi(\boldsymbol{\theta})]/\mathbf{g}_{n}(\underline{\mathbf{x}})$$

C. Most of the time it is not practical to compute $g_n(\underline{x})$. However, this is not a problem because *with respect to the posterior distribution it is a constant*. That is:

$$\xi(\boldsymbol{\theta}|\underline{\mathbf{x}}) \propto \mathbf{f}_{n}(\underline{\mathbf{x}}|\boldsymbol{\theta})\xi(\boldsymbol{\theta})$$

B. The Confusion Over Likelihood Functions!

Consider the standard development of MLE in most textbooks. The Likelihood setup for the Bernoulli distribution is:

$$L(p \mid \underline{x}) = \prod_{i=1}^{n} f(x_{1} \mid p) f(x_{2} \mid p) ... f(x_{n} \mid p) = p^{\sum_{i=1}^{n} X_{i}} (1 - p)^{n - \sum_{i=1}^{n} X_{i}}$$

this is usually written as $L(p | \underline{x}) = p^{y}(1 - p)^{n-y}$ where $y = \sum_{i=1}^{n} X_{i}$. Standard Calculus can

now be used to solve for the value of p that maximizes L(p|x); namely,

$$\hat{\mathbf{p}} = \frac{\sum_{i=1}^{n} \mathbf{X}_{i}}{n} = \overline{\mathbf{X}}_{n}$$

1. Note that $L(\mathbf{p}|\underline{\mathbf{x}})$ is not a probability distribution because \mathbf{p} is NOT a random variable! It is simply a *function*. In this example, even if \mathbf{p} is treated as a random variable $L(\mathbf{p}|\underline{\mathbf{x}})$ is not a proper probability distribution. Although $L(\mathbf{p}|\underline{\mathbf{x}}) \ge 0$ it does not integrate to 1:

$$\int_{0}^{1} L(p \mid \underline{x}) dp = \int_{0}^{1} p^{y} (1-p)^{n-y} dp = \frac{\Gamma(y+1)\Gamma(n-y+1)}{\Gamma(n+2)}$$

2. The joint distribution of the sample is:

$$f_{n}(\underline{x} \mid p) = \prod_{i=1}^{n} f(x_{1} \mid p) f(x_{2} \mid p) ... f(x_{n} \mid p) = p^{\sum_{i=1}^{n} X_{i}} (1 - p)^{n - \sum_{i=1}^{n} X_{i}}$$

Technically:

$$f_{n}(\underline{x} \mid p) = \begin{cases} \sum_{i=1}^{n} X_{i} & x_{i} = 0, 1 \\ p^{\sum_{i=1}^{n} X_{i}} & (1 - p)^{n - \sum_{i=1}^{n} X_{i}} & x_{2} = 0, 1 \\ 0 & \text{otherwise} & \dots \\ & x_{n} = 0, 1 \end{cases}$$

This is a probability distribution because $f_n(\underline{x}|p) \ge 0$ and

$$\sum_{X_1=0}^{1} \sum_{X_2=0}^{1} \sum_{X_3=0}^{1} \dots \sum_{X_n=0}^{1} p^{\sum_{i=1}^{n} X_i} (1 - p)^{n - \sum_{i=1}^{n} X_i} = 1$$

3. Confusion reigns because $f_n(\underline{x}|p)$ and $L(p|\underline{x})$ are the same equation for a *random sample from a known parametric distribution*. What shifts is what variables are taken as *random* and the Likelihood function is *not* a probability distribution it is a *function*.

4. Gary King resolves this problem by simply stating as an axiom what is true in practice that:

$$L(\theta \mid \underline{x}) \propto f_n(\underline{x} \mid \theta)$$

so that

$$\xi(\theta|\underline{x}) \propto f_n(\underline{x}|\theta)\xi(\theta) \propto L(p|\underline{x})\xi(\theta)$$